

Chceme odvodiť vzťah:

$$c_{m+1}(n) = \sum_k^1 h_{mr}(k-2n) c_m(k)$$

Vieme, že platí:

$$\varphi_{m,n}(t) = 2^{-m/2} \varphi(2^{-m}t - n)$$

$$\varphi(t) = \sqrt{2} \sum_{n=-\infty}^{\infty} h_{mr}(n) \varphi(2t - n)$$

Vynásobíme obe strany druhej rovnice $2^{-m/2}$ a za t dosadíme $2^{-m}t - n$:

$$2^{-m/2} \varphi(2^{-m}t - n) = 2^{-m/2} \cdot 2^{1/2} \sum_k h_{mr}(k) \varphi(2(2^{-m}t - n) - k)$$

$$\begin{aligned} \varphi_{m,n}(t) &= \sum_k h_{mr}(k) 2^{-(m-1)/2} \varphi(2^{-(m-1)}t - 2n - k) = \\ &= \sum_k h_{mr}(k) \varphi_{m-1,2n+k} \end{aligned}$$

$$\begin{aligned} c_m(n) &= \langle f(t), \varphi_{m,n}(t) \rangle = \left\langle f(t), \sum_k h_{mr}(k) \varphi_{m-1,2n+k} \right\rangle = \sum_k h_{mr}(k) \langle f(t), \varphi_{m-1,2n+k} \rangle = \\ &= \sum_k h_{mr}(k) c_{m-1}(2n+k) = \sum_k h_{mr}(k-2n) c_{m-1}(k) \end{aligned}$$

T.j: $c_{m+1}(n) = \sum_k h_{mr}(k-2n) c_m(k)$

DWT v maticovom tvare.

Uvažujme nasledovné tvary rovníc:

Rozklad(analýza):
$$c_{m+1}(n) = \sum_k \tilde{h}_{mr}(k-2n)c_m(k) \quad d_{m+1}(n) = \sum_k \tilde{g}_{mr}(k-2n)c_m(k)$$

Rekonštrukcia(syntéza):
$$c_m(n) = \sum_k h_{mr}(n-2k)c_{m+1}(k) + \sum_k g_{mr}(n-2k)d_{m+1}(k)$$

Tieto vzťahy môžeme prepísať do maticového tvaru ako transformácie:

$$\begin{pmatrix} \mathbf{C}_{m+1} \\ \mathbf{D}_{m+1} \end{pmatrix} = \mathbf{T}_a \mathbf{C}_m \quad \mathbf{C}_m = \mathbf{T}_s \begin{pmatrix} \mathbf{C}_{m+1} \\ \mathbf{D}_{m+1} \end{pmatrix}$$

, kde T_a , T_s sú **štvorcové** transformačné matice pre analýzu, resp. pre syntézu a $\mathbf{C}_m$ resp. $\mathbf{D}_m$ sú stĺpcové vektory (matice) :

$$\mathbf{C}_m = (c_m(0), c_m(1), \dots, c_m(N_m-1))^T$$

$$\mathbf{D}_m = (d_m(0), d_m(1), \dots, d_m(N_m-1))^T$$

kde veľkosť vektorov je:

$$N_m = 2^{-m} N_0$$

Pozn.: v d'alšom texte budeme $\tilde{h}_{mr}$, h_{mr} , g_{mr} , $\tilde{g}_{mr}$ používať bez označenia "**mr**".

Maticový zápis pri periodickom rozšírení signálu

$$\tilde{\mathbf{H}}_m = \overbrace{\begin{pmatrix} \tilde{h}(0) & \tilde{h}(1) & \dots & \dots & \dots & \tilde{h}(-1) \\ \dots & \tilde{h}(-1) & \tilde{h}(0) & \tilde{h}(1) & \dots & \dots \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ \dots & \dots & \dots & \tilde{h}(-1) & \tilde{h}(0) & \tilde{h}(1) \end{pmatrix}}^{N_m} \quad \tilde{\mathbf{G}}_m = \overbrace{\begin{pmatrix} \tilde{g}(0) & \tilde{g}(1) & \dots & \dots & \dots & \tilde{g}(-1) \\ \dots & \tilde{g}(-1) & \tilde{g}(0) & \tilde{g}(1) & \dots & \dots \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ \dots & \dots & \dots & \tilde{g}(-1) & \tilde{g}(0) & \tilde{g}(1) \end{pmatrix}}^{N_m} \left. \vphantom{\begin{pmatrix} \tilde{g}(0) & \tilde{g}(1) & \dots & \dots & \dots & \tilde{g}(-1) \\ \dots & \tilde{g}(-1) & \tilde{g}(0) & \tilde{g}(1) & \dots & \dots \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ \dots & \dots & \dots & \tilde{g}(-1) & \tilde{g}(0) & \tilde{g}(1) \end{pmatrix}} \right\} \frac{N_m}{2}$$

$$\mathbf{H}_m = N_m \left\{ \begin{pmatrix} h(0) & \vdots & \dots & \vdots \\ h(1) & h(-1) & \dots & \vdots \\ \vdots & h(0) & \dots & \vdots \\ \vdots & h(1) & \dots & h(-1) \\ \vdots & \vdots & \dots & h(0) \\ h(-1) & \vdots & \dots & h(1) \end{pmatrix} \right. \quad \mathbf{G}_m = N_m \left\{ \begin{pmatrix} g(0) & \vdots & \dots & \vdots \\ g(1) & g(-1) & \dots & \vdots \\ \vdots & g(0) & \dots & \vdots \\ \vdots & g(1) & \dots & g(-1) \\ \vdots & \vdots & \dots & g(0) \\ g(-1) & \vdots & \dots & g(1) \end{pmatrix} \right.$$

Analýza: $\mathbf{C}_{m+1} = \tilde{\mathbf{H}}_m \mathbf{C}_m \quad \mathbf{D}_{m+1} = \tilde{\mathbf{G}}_m \mathbf{C}_m$

$$\begin{pmatrix} \mathbf{C}_{m+1} \\ \mathbf{D}_{m+1} \end{pmatrix} = \begin{pmatrix} \tilde{\mathbf{H}}_m \\ \tilde{\mathbf{G}}_m \end{pmatrix} \mathbf{C}_m \quad \rightarrow \quad \mathbf{T}_a = \begin{pmatrix} \tilde{\mathbf{H}}_m \\ \tilde{\mathbf{G}}_m \end{pmatrix}$$

Syntéza: $\mathbf{C}_m = (\mathbf{H}_m \quad \mathbf{G}_m) \begin{pmatrix} \mathbf{C}_{m+1} \\ \mathbf{D}_{m+1} \end{pmatrix} \quad \rightarrow \quad \mathbf{T}_s = (\mathbf{H}_m \quad \mathbf{G}_m)$

V prípade Haarovej DWT:

- **Rozklad (= dopredná transformácia)**

$$c_{m+1}(n) = \sum_k \tilde{h}_{mr}(k-2n) c_m(k)$$

$$d_{m+1}(n) = \sum_k \tilde{g}_{mr}(k-2n) c_m(k)$$

$$\mathbf{C}_{m+1} = \tilde{\mathbf{H}}_m \mathbf{C}_m$$

$$\mathbf{D}_{m+1} = \tilde{\mathbf{G}}_m \mathbf{C}_m$$

$$\tilde{h}_{mr} = \frac{\sqrt{2}}{2} (1, 1)$$

$$\tilde{g}_{mr} = \frac{\sqrt{2}}{2} (1, 1)$$

$$\tilde{\mathbf{H}}_m = \frac{\sqrt{2}}{2} \begin{pmatrix} 1 & 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & 1 \end{pmatrix}$$

$$\tilde{\mathbf{G}}_m = \frac{\sqrt{2}}{2} \begin{pmatrix} 1 & -1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & -1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & -1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & -1 \end{pmatrix}$$

Príklad vstupného signálu:

$$c_0(n) = (1, 2, 3, 4, 5, 6, 7, 8)^T$$

$$N_0 = 8$$

$$c_1(n) = \frac{\sqrt{2}}{2} (3, 7, 11, 15)^T$$

$$d_1(n) = \frac{\sqrt{2}}{2} (-1, -1, -1, -1)^T$$

$$\mathbf{T}_a = \begin{pmatrix} \tilde{\mathbf{H}}_m \\ \tilde{\mathbf{G}}_m \end{pmatrix} = \frac{\sqrt{2}}{2} \begin{pmatrix} 1 & 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & 1 \\ 1 & -1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & -1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & -1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & -1 \end{pmatrix}$$

Reprezentácia signálu po jednom transformačnom kroku:

$$(c_1(n), d_1(n)) = \frac{\sqrt{2}}{2} (3, 7, 11, 15, -1, -1, -1, -1)^T$$

→ Ďalšie kroky analogicky ... (ešte 2 kroky)

• **Rekonštrukcia (= spätná transformácia)**

$$c_m(n) = \sum_k h_{mr}(n-2k)c_{m+1}(k) + \sum_k g_{mr}(n-2k)d_{m+1}(k)$$

$$\mathbf{C}_m = \begin{pmatrix} \mathbf{H}_m & \mathbf{G}_m \end{pmatrix} \begin{pmatrix} \mathbf{C}_{m+1} \\ \mathbf{D}_{m+1} \end{pmatrix} = \mathbf{T}_s \begin{pmatrix} \mathbf{C}_{m+1} \\ \mathbf{D}_{m+1} \end{pmatrix}$$

$$\mathbf{H}_m = \frac{\sqrt{2}}{2} \begin{pmatrix} 1 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 1 \end{pmatrix} \quad \mathbf{G}_m = \frac{\sqrt{2}}{2} \begin{pmatrix} 1 & 0 & 0 & 0 \\ -1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & -1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & -1 \end{pmatrix} \quad \mathbf{T}_s = \frac{\sqrt{2}}{2} \begin{pmatrix} 1 & 0 & 0 & 0 & 1 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & -1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & -1 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 1 & 0 & 0 & 0 & -1 \end{pmatrix}$$

Vektory bázy, do ktorej sme transformovali, sú stĺpcové vektory z matice $\mathbf{T}_s$.

Všeobecne (opakovanie)

$$\mathbf{T}_a \mathbf{T}_s = \mathbf{I}_N = \mathbf{T}_s \mathbf{T}_a$$

Vyjadrame:

$$\mathbf{I}_N = \begin{pmatrix} \mathbf{I}_{N/2} & \mathbf{0}_{N/2} \\ \mathbf{0}_{N/2} & \mathbf{I}_{N/2} \end{pmatrix} = \mathbf{T}_a \mathbf{T}_s = \begin{pmatrix} \tilde{\mathbf{H}} \\ \tilde{\mathbf{G}} \end{pmatrix} (\mathbf{H} \quad \mathbf{G}) = \begin{pmatrix} \tilde{\mathbf{H}}\mathbf{H} \\ \tilde{\mathbf{G}} \end{pmatrix} (\mathbf{H} \quad \mathbf{G}) = \begin{pmatrix} \tilde{\mathbf{H}}\mathbf{H} & \tilde{\mathbf{H}}\mathbf{G} \\ \tilde{\mathbf{G}}\mathbf{H} & \tilde{\mathbf{G}}\mathbf{G} \end{pmatrix}$$

z čoho vyplýva:

$$\tilde{\mathbf{H}}\mathbf{H} = \tilde{\mathbf{G}}\mathbf{G} = \mathbf{I} \quad \tilde{\mathbf{H}}\mathbf{G} = \tilde{\mathbf{G}}\mathbf{H} = \mathbf{0}$$

T.j. impulzové charakteristiky filtrov sú ortogonálne k párnym posunom svojich duálov a ortogonálne navzájom „nakříž“ = podmienky *biortogonality*.

Pre Ortogonálne DWT platí nasledovná podmienka :

$$\tilde{h}_{mr}(n) = h_{mr}(n), \quad \tilde{g}_{mr}(n) = g_{mr}(n) \quad g_{mr}(n) = \pm(-1)^n h_{mr}(M-n)$$